



**PLATTE RIVER RECOVERY IMPLEMENTATION PROGRAM
TECHNICAL SPECIFICATIONS**

1
2
3 **SUBJECT:** Annual LiDAR and Aerial Photography
4 **POINT OF CONTACT:** Justin Brei
5 Headwaters Corporation
6 4111 4th Ave, Suite 6
7 Kearney, NE 68845
8 (308) 237-5728 Ext. 4
9 breij@headwaterscorp.com

10
11 **I. OVERVIEW**

12 The Platte River Recovery Implementation Program (**Program**) was initiated on January 1, 2007
13 between Nebraska, Wyoming, and Colorado and the Department of the Interior to address
14 endangered species issues in the central and lower Platte River basin. The species considered in
15 the Program, referred to as “target species”, are the whooping crane, piping plover, interior least
16 tern, and pallid sturgeon.

17
18 A Governance Committee (**GC**) has been established that reviews, directs, and provides
19 oversight for activities undertaken during the Program. The GC is comprised of one
20 representative from each of the three states, three water user representatives, two representatives
21 from environmental groups, and two members representing federal agencies. The GC named Dr.
22 Jerry Kenny to serve as the Program Executive Director (**ED**). Dr. Kenny established
23 Headwaters Corporation as the staffing mechanism for Program. Program staff are located in
24 Nebraska and Colorado and are responsible for assisting in carrying out the various Program-
25 related activities.

26
27 Annual aerial photography is a requirement of the Program's Adaptive Management Plan and an
28 integral part of several research and monitoring protocols. This annual aerial photography is
29 typically acquired in June when piping plovers and interior least terns are nesting.

30
31 The Program acquired LiDAR for the central Platte River in the spring of 2009 as a part of
32 baseline data collection. In the fall of 2010, the Program again acquired LiDAR over a portion
33 of the original acquisition in order to assess change within the river banks. The Program will
34 acquire LiDAR over this area annually to document change in channel characteristics and to
35 assist in habitat availability evaluations for target species. Additional aerial photography that
36 accompanies the LiDAR acquisition will assist in, and add value to the evaluation.

37
38 **II. PROJECT DESCRIPTION**

39 Annual color-infrared (**CIR**) orthophotography will be used to help document habitat conditions
40 for Program target species. In addition, it can be used to document summertime vegetation
41 characteristics throughout the system, on Program lands, and within managed areas. For
42 example, bare sand substrates will be identified that may be potential least tern and piping plover
43 nesting habitat, and major management changes can be tracked, such as tree clearing or cropland



44 changes. Changes in available tern/plover nesting habitat will be tracked throughout the First
45 Increment. Information gained from aerial photography will also be used in conjunction with
46 measurements taken at specific sites on the ground that relate to vegetation establishment on
47 sandbars, height of sandbars, etc. CIR photos will be used to estimate the land use/land cover
48 types present (e.g., amount of grassland, forest, etc). This CIR photography will also be used for
49 channel morphology measurements. The photos will be used to help measure parameters such as
50 channel width, bank position, island position and stability, hydraulic geometry characteristics of
51 width, and track changes associated with management techniques. Photos will be taken on an
52 annual basis between late May and late June with flows at or near 1,200 cfs (i.e., Program target
53 flow levels during this time of year). Aerial photography will be acquired in color-infrared at a
54 two-foot digital resolution. The contractor will work with Program staff during the acquisition
55 window to schedule flights in accordance with these requirements.

56
57 Acquiring LiDAR within the river channel every year allows the Program to evaluate the effects
58 of annual flow conditions on channel morphology. These analyses will affect how the Program
59 uses its limited water resources to manage habitat. CIR orthophotography will be acquired in
60 combination with the LiDAR acquisition. This photography will be used as a tool to further
61 assess both the quality and accuracy of the LiDAR, and as an additional data set for evaluating
62 geomorphic change. Since the LiDAR and this additional photography acquisition will take
63 place under low-flow conditions, this photography will also provide a picture of the Platte River
64 under different conditions than the Program's annual spring aerial photography acquisition. CIR
65 photography acquired in combination with the LiDAR also provides a way to examine land
66 cover types and condition for use in modeling efforts. Aerial photography will be acquired in
67 color-infrared at a two-foot (or better) digital resolution, and will be acquired concurrently with
68 the LiDAR. Contractor will work with Program staff during the acquisition window to schedule
69 flights in accordance with these requirements.

70

71 **III. SCOPE OF WORK**

72 Minimum LiDAR and digital aerial imagery technical specifications follow:

73

74 **1) Schedule**

75

76 a) Sub-Project 1 - November/December concurrent LiDAR and Aerial photography.

77 i) LiDAR and imagery will be acquired each year in November/December from 2011
78 through 2014 under leaf-off and low Platte River flow conditions. Contractor must be
79 flexible and work with Program staff during that time to schedule flights such that
80 river flows in the project area are as low as possible (ideally under 1,000 cfs).

81 ii) Imagery will be acquired on cloud-free days with the sun at a sufficient angle to
82 reduce the effect of shadows from trees and structures and efforts should be made to
83 reduce sun glare on water surfaces.

84 iii) Imagery will be acquired in combination with LiDAR such that the imagery reflects
85 the condition of the river during the LiDAR acquisition. River conditions can change
86 daily, and imagery must be flown at least the same day, if not at the exact same time
87 as the LiDAR.



- 88 iv) The acquisition area must be free of snow and ice, and extraneous environmental
89 conditions such as rain, fog or smoke should be avoided.
90 v) Final delivery of product will be within 60 days of final acquisition flight each year.
91

92 b) Sub-Project 2 - May/June Aerial photography.

- 93 i) Imagery will be acquired each year between May 15 and June 30. Contractor must be
94 flexible and work with Program staff during that time to schedule flights such that
95 river flows in the project area are as close to 1,200 cfs as possible.
96 ii) Imagery will be acquired on cloud-free days with the sun at a sufficient angle to
97 reduce the effect of shadows from trees and structures and efforts should be made to
98 reduce sun glare on water surfaces.
99 iii) Final delivery of product will be within 30 days of final acquisition flight each year.
100

101 **2) Project Area**

- 102
103 a) The area of interest for Sub-Project 1 consists of an area generally between the high
104 banks of the Platte River beginning near the junction of U.S. Highway 283 and Interstate
105 80 near Lexington, Nebraska, and extending eastward to near Chapman, Nebraska
106 (approximately 127 square miles). A polygon shapefile of the acquisition area is
107 included on the Program website (www.platteriverprogram.org) in the same location as
108 this solicitation.
109 b) The area of interest for Sub-Project 2 consists of an area 3.5 miles either side of the
110 centerline of the Platte River beginning at the junction of U.S. Highway 283 and
111 Interstate 80 near Lexington, Nebraska, and extending eastward to Chapman, Nebraska
112 (approximately 750 square miles). A polygon shapefile of the acquisition area is
113 included on the Program website (www.platteriverprogram.org) in the same location as
114 this solicitation.
115

116 **3) Sub-Project 1 Technical Specifications**

117
118 a) LiDAR Technical Specifications

- 119 i) The LiDAR data will be collected at a mean resolution of 2.3 ft (0.7 m) GSD or
120 better.
121 ii) The contractor shall ensure that the area of interest is fully and sufficiently covered
122 with no data voids due to gaps between flightlines or system malfunction.
123 iii) Data voids in the bare-earth not caused by classification of geographic features shall
124 not exceed three times the point spacing. Data voids of this size are sufficient
125 reason to reject the dataset.
126 iv) LiDAR data should be classified using the following ASPRS Standard LiDAR
127 Point Classes:
128 • Class 1 – Unclassified
129 • Class 2 – Ground
130 • Class 7 – Low point and noise



- 131 • Class 9 – Water
132 • Class 12 – Overlap
133 (1) Class 1 will be used for feature points that are not in Classes 2, 7, 9, or 12.
134 These typically represent returns from man-made structures, vegetation etc.
135 (2) Class 2 will be used for feature points that represent the bare-earth.
136 (3) Class 7 will be used for artifacts that do not represent the ground, manmade
137 structures or vegetation. Typically these are extraneous points that are either
138 below, or well above the surface not representing any true feature.
139 (4) Class 9 will be used to identify points found within water bodies, including
140 streams and rivers.
141 (5) Class 12 will be used for LiDAR points in the overlap portion of flight lines that
142 have been removed due to redundancy (if necessary).
143 (6) No points shall be deleted from the LAS files.
144 v) Bare-earth classification shall adhere to the following specifications using both
145 automated and manual filtering classification routines:
146 • 90% of artifacts classified
147 • 95% of outliers classified
148 • 95% of vegetation classified
149 • 98% of building classified
150 vi) Special attention must be applied to the classification process due to the geographic
151 nature of the project area which consists of extremely flat terrain mixed with
152 important hydrographic characteristics. Channel geometry of streams and drainage
153 features must be maintained as well as the ability to identify sand bar features
154 within the Platte River. Dense vegetation data voids must also be minimized by the
155 automatic removal process and “over smoothing” due to aggressive classification
156 must be avoided.
157 vii) Vertical accuracy for LiDAR will meet or exceed 3.6 in (9.2 cm) RMSE (Accuracy_z
158 = 7.1 in (0.18 m) at the 95% confidence level).
159 viii) Horizontal accuracy for LiDAR will meet or exceed 1.97 ft (0.6 m) RMSE
160 (Accuracy_r = 3.41 ft (1.04 m) at the 95% confidence level).
161 ix) The vertical datum for LiDAR is NAVD88 (Geoid03), and the horizontal datum is
162 Nebraska State Plane (1983). Elevation and projection in feet.
163
164 b) Aerial Photography Technical Specifications
165 i) The imagery will be two-foot (0.61m) pixel resolution or better.
166 ii) The imagery will be color-infrared.
167 iii) The imagery will be ortho-rectified and seamless, and will be tone-balanced with
168 adjacent images across the project area.
169 iv) Imagery will be acquired on cloud-free days with the sun at a sufficient angle to
170 reduce the effect of shadows from trees and structures and efforts should be made to
171 reduce sun glare on water surfaces.
172 v) The imagery will be projected in Nebraska State Plane Feet (1983 datum).



173 vi) The imagery must be acquired concurrently with the LiDAR so as to reflect river
174 conditions during acquisition. The imagery must be collected at least the same day, if
175 not at the exact same time, as the LiDAR.

176 **4) Sub-Project 2 Technical Specifications**

177 a) Aerial Photography Technical Specifications

- 178 i) The imagery will be two-foot (0.61m) pixel resolution or better.
- 179 ii) The imagery will be color-infrared.
- 180 iii) The imagery will be ortho-rectified and seamless, and will be tone-balanced with
181 adjacent images across the project area.
- 182 iv) Imagery will be acquired on cloud-free days with the sun at a sufficient angle to
183 reduce the effect of shadows from trees and structures and efforts should be made to
184 reduce sun glare on water surfaces.
- 185 v) The imagery will be projected in Nebraska State Plane Feet (1983 datum).

186
187 **5) Project Deliverables**

188
189 a) LiDAR

- 190 i) LiDAR point data meeting or exceeding 2.3 ft (0.7 m) GSD resolution in a classified
191 LAS file format and adhering to the technical specifications in 3) above. LAS file
192 projected to Nebraska State Plane Feet (1983 datum) and vertical reference NAVD88
193 feet. Classified LAS file will include all LiDAR points, including first and last
194 returns.
- 195 ii) Daily reports during acquisition that display all flight lines, as well as completed
196 areas. Once acquisition is complete, a project summary report that shows time and
197 date of all flightline acquisitions. Time of day, not just the day, is important to match
198 river flow condition to acquisition.
- 199 iii) Tiling scheme will be provided to contractor. Tiles are 2,500 meters x 2,500 meters
200 and will match existing Program LiDAR tiles.
- 201 iv) Bare-earth digital elevation model raster (3-foot cell size) of project area, projected in
202 Nebraska State Plane coordinate system – elevation and projection in feet.

203
204 b) Imagery

- 205 i) Color-infrared digital orthophotography with a two-foot pixel resolution (or better),
206 covering the entire project area seamlessly and without data gaps.
- 207 ii) The imagery should be geo-referenced and provided in GeoTIFF (.tif) format.
- 208 iii) Shapefiles displaying photocenters and flight dates and times for image acquisitions.
209 Time of day, not just the day, is important to match river flow condition to
210 acquisition.
- 211 iv) Compressed imagery mosaic (.sid). Typically entire reach compiled into one mosaic,
212 but may be split due to file size.

213
214
215



- 216 c) LiDAR and Imagery
217 i) FGDC-compliant metadata to include, but not limited to: flight dates and times, flight
218 altitude, camera system information, LiDAR system information, aircraft information,
219 imagery resolution, LiDAR point density, horizontal accuracy, post-processing
220 software and steps, and horizontal and vertical control references.
221 ii) All LiDAR data, photography, and supplemental products will be delivered on USB
222 external hard drives and will become the property of the Program. All media and data
223 collected under the contract shall be the sole property of and can be freely distributed
224 by the Program. No restrictions shall be placed on the data by the contractor.

225 **6) Permits and Clearances**
226

- 227 a) It is the contractor's responsibility to file all required flight plans and obtain all necessary
228 approvals to fly over and acquire aerial imagery and LiDAR in the project area.
229
230

